

4 Boosting

Gradient Boosting is an iterative functional gradient descent algorithm that optimizes a risk function over function space. Let \mathcal{X} be the input space, \mathcal{Y} be the output space. Suppose we wish to find $g = \sum_{t=1}^T \alpha_t h_t$ as an ensemble of weak prediction models $h_t \in H$ that minimizes $\hat{\mathcal{R}}_S(g)$, where $\hat{\mathcal{R}}_S$ is an empirical risk function on $\text{Span}(H)$ that depends on labeled sample $S = ((x_i, y_i))_{i=1}^m \in (\mathcal{X} \times \mathcal{Y})^m$. We first initialize $g_1 = 0$ and for each iteration $t = 1, 2, \dots, T$ update $g_{t+1} = g_t + \alpha_t h_t$, where

$$h_t \in \underset{h \in H}{\operatorname{argmin}} \left. \frac{\partial}{\partial \alpha} \hat{\mathcal{R}}_S(g_t + \alpha h) \right|_{\alpha=0}, \quad \alpha_t \in \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}} \hat{\mathcal{R}}_S(g_t + \alpha h_t)$$

4.1 AdaBoost

In binary classification problem $\mathcal{Y} = \{\pm 1\}$, AdaBoost aims to minimize the empirical **exponential risk** $\hat{\mathcal{R}}_S^{\text{exp}}(g) = \frac{1}{m} \sum_{i=1}^m e^{-y_i g(x_i)}$ over $g \in \text{Span}(H)$ for which $H \subset \{\pm 1\}^{\mathcal{X}}$ is a hypothesis set of weak classifiers. Following the procedure of gradient boosting, it first initialize $g_1 = 0$ and for each iteration $t = 1, 2, \dots, T$ update $g_{t+1} = g_t + \alpha_t h_t$, where

$$\begin{aligned} h_t \in \underset{h \in H}{\operatorname{argmin}} \left. \frac{\partial}{\partial \alpha} \hat{\mathcal{R}}_S^{\text{exp}}(g_t + \alpha h) \right|_{\alpha=0} &= \underset{h \in H}{\operatorname{argmin}} \left. \frac{\partial}{\partial \alpha} \sum_{i=1}^m e^{-y_i g_t(x_i) - \alpha y_i h(x_i)} \right|_{\alpha=0} \\ &= \underset{h \in H}{\operatorname{argmin}} - \sum_{i=1}^m e^{-y_i g_t(x_i)} y_i h(x_i) = \underset{h \in H}{\operatorname{argmin}} - Z_t \mathbb{E}_{i \sim D_t} [y_i h(x_i)] \\ &= \underset{h \in H}{\operatorname{argmin}} Z_t (2\mathbb{P}_{i \sim D_t} [h(x_i) \neq y_i] - 1) = \underset{h \in H}{\operatorname{argmin}} \mathbb{P}_{i \sim D_t} [h(x_i) \neq y_i], \\ \alpha_t \in \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}} \hat{\mathcal{R}}_S^{\text{exp}}(g_t + \alpha h_t) &= \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}} \sum_{i=1}^m e^{-y_i g_t(x_i) - \alpha y_i h_t(x_i)} \\ &= \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}} Z_t \mathbb{E}_{i \sim D_t} [e^{-\alpha y_i h_t(x_i)}] = \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}} Z_t (\epsilon_t e^\alpha + (1 - \epsilon_t) e^{-\alpha}) = \left\{ \log \sqrt{\frac{1 - \epsilon_t}{\epsilon_t}} \right\} \end{aligned}$$

where $Z_t = \sum_{i=1}^m e^{-y_i g_t(x_i)}$, D_t is a probability distribution on $\llbracket 1, m \rrbracket$ given by $D_t(i) = e^{-y_i g_t(x_i)} / Z_t$, and $\epsilon_t = \mathbb{P}_{i \sim D_t} [h_t(x_i) \neq y_i]$ is the error of h_t on training sample weighted by the distribution D_t . Note that $Z_1 = m$ and

$$Z_{t+1} = \sum_{i=1}^m e^{-y_i g_{t+1}(x_i)} = \sum_{i=1}^m e^{-y_i g_t(x_i) - \alpha_t y_i h_t(x_i)} = Z_t \mathbb{E}_{i \sim D_t} [e^{-\alpha_t y_i h_t(x_i)}]$$

Denote

$$\gamma_t = \mathbb{E}_{i \sim D_t} [e^{-\alpha_t y_i h_t(x_i)}] = \epsilon_t e^{\alpha_t} + (1 - \epsilon_t) e^{-\alpha_t} = 2\sqrt{\epsilon_t(1 - \epsilon_t)}$$

Then $Z_{t+1} = \gamma_t Z_t$, and

$$\begin{aligned} D_{t+1}(i) &= Z_{t+1}^{-1} e^{-y_i g_{t+1}(x_i)} = Z_{t+1}^{-1} e^{-y_i g_t(x_i) - \alpha_t y_i h_t(x_i)} = Z_{t+1}^{-1} Z_t D_t(i) e^{-\alpha_t y_i h_t(x_i)} \\ &= \gamma_t^{-1} D_t(i) e^{-\alpha_t y_i h_t(x_i)} \end{aligned}$$

This leads to Algorithm.1.

Algorithm 1 AdaBoost

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1: procedure ADABOOST( $S = ((x_i, y_i))_{i=1}^m$ )
2:   for  $i \leftarrow 1$  to  $m$  do
3:      $D_1(i) \leftarrow \frac{1}{m}$ 
4:   end for
5:   for  $t \leftarrow 1$  to  $T$  do
6:      $h_t \leftarrow$  base classifier in  $H$  with small error  $\epsilon_t = \mathbb{P}_{i \sim D_t}[h_t(x_i) \neq y_i]$ .
7:      $\alpha_t \leftarrow \frac{1}{2} \log \frac{1-\epsilon_t}{\epsilon_t}$ 
8:      $\gamma_t \leftarrow 2\sqrt{\epsilon_t(1-\epsilon_t)}$  ▷ normalization factor
9:     for  $i \leftarrow 1$  to  $m$  do
10:       $D_{t+1}(i) \leftarrow \gamma_t^{-1} D_t(i) \exp(-\alpha_t y_t h_t(x_i))$ 
11:    end for
12:   end for
13:    $g \leftarrow \sum_{t=1}^T \alpha_t h_t$ 
14:   return  $g$ 
15: end procedure
```
